

Model 482C24 SENSOR SIGNAL CONDITIONER Installation and Operating Manual

For assistance with the operation of this product, contact PCB Piezotronics, Inc.

Toll-free: 800-828-8840 24-hour SensorLine: 716-684-0001

> Fax: 716-684-0987 E-mail: info@pcb.com Web: www.pcb.com







Warranty, Service, Repair, and Return Policies and Instructions

The information contained in this document supersedes all similar information that may be found elsewhere in this manual.

Total Customer Satisfaction – PCB Piezotronics guarantees Total Customer Satisfaction. If, at any time, for any reason, you are not completely satisfied with any PCB product, PCB will repair, replace, or exchange it at no charge. You may also choose to have your purchase price refunded in lieu of the repair, replacement, or exchange of the product.

Service – Due to the sophisticated nature of the sensors and associated instrumentation provided by PCB Piezotronics, user servicing or repair is not recommended and, if attempted, may void the factory warranty. Routine maintenance, such as the cleaning of electrical connectors, housings, mounting surfaces with solutions and techniques that will not harm the physical material of construction, is acceptable. Caution should be observed to insure that liquids are not permitted to migrate into devices that are not hermetically sealed. Such devices should only be wiped with a dampened cloth and never submerged or have liquids poured upon them.

Repair – In the event that equipment becomes damaged or ceases to operate, arrangements should be made to return the equipment to PCB Piezotronics for repair. User servicing or repair is not recommended and, if attempted, may void the factory warranty.

Calibration – Routine calibration of sensors and associated instrumentation is

recommended as this helps build confidence in measurement accuracy and acquired data. Equipment calibration cycles are typically established by the users own quality regimen. When in doubt about a calibration cycle, a good "rule of thumb" is to recalibrate on an annual basis. It is also good practice to recalibrate after exposure to any severe temperature extreme, shock, load, or other environmental influence, or prior to any critical test.

PCB Piezotronics maintains an ISO-9001 certified metrology laboratory and offers calibration services, which are accredited by A2LA to ISO/IEC 17025, with full traceablility to N.I.S.T. In addition to the normally supplied calibration, special testing is also available, such as: sensitivity at elevated cryogenic temperatures, phase extended response, high frequency response, extended range, leak testing, hydrostatic pressure testing, and others. For information on standard recalibration services or special testing, contact your local PCB Piezotronics distributor, sales representative, factory customer service representative.

Returning Equipment – Following these procedures will insure that your returned materials are handled in the most expedient manner. Before returning any equipment to PCB Piezotronics, contact your local distributor, sales representative, or factory customer service representative to obtain a Return

Materials Authorization (RMA) Number. This RMA number should be clearly marked on the outside of all package(s) and on the packing list(s) accompanying the shipment. A detailed account of the nature of the problem(s) being experienced with the equipment should also be included inside the package(s) containing any returned materials.

A Purchase Order, included with the returned materials, will expedite the turn-around of serviced equipment. It is recommended to include authorization on the Purchase Order for PCB to proceed with any repairs, as long as they do not exceed 50% of the replacement cost of the returned item(s). PCB will provide a price quotation or replacement recommendation for any item whose repair costs would exceed 50% of replacement cost, or any item that is not economically feasible to repair. For routine calibration services, the Purchase Order should include authorization to proceed and return at current pricing, which can be obtained from a factory customer service representative.

Warranty – All equipment and repair services provided by PCB Piezotronics, Inc. are covered by a limited warranty against defective material and workmanship for a period of one year from date of original purchase. Contact

PCB for a complete statement of our warranty. Expendable items, such as batteries and mounting hardware, are not covered by warranty. Mechanical damage to equipment due to improper use is not covered by warranty. Electronic circuitry failure caused by the introduction of unregulated or improper excitation power or electrostatic discharge is not covered by warranty.

Contact Information – International customers should direct all inquiries to their local distributor or sales office. A complete list of distributors and offices be found at www.pcb.com. Customers within the United States may contact their local sales representative or customer factory service representative. A complete list of sales representatives can be found www.pcb.com. Toll-free telephone numbers for a factory customer service representative, in the division responsible for this product, can be found on the title page at the front of this manual. Our ship to address and general contact numbers are:

PCB Piezotronics, Inc. 3425 Walden Ave. Depew, NY 14043 USA Toll-free: (800) 828-8840

24-hour SensorLineSM: (716) 684-0001

Website: www.pcb.com E-mail: info@pcb.com

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ECN: 17900

Model	Number
401	0004

SENSOR SIGNAL CONDITIONER

Revision: A ECN #: 45020

ı	482C24		OLIVO	OIL GIGHAL	UU
	Performance		ENGLISH	<u>SI</u>	
ı	Channels		4	4	
ı	Sensor Input Type(s)		ICP®, Voltage	ICP®, Voltage	
ı	Voltage Gain		x0.1 to x200	x0.1 to x200	
ı	Accuracy(Gain, x0.1 to x	(0.4)	± 5 %	± 5 %	
ı	Accuracy(Gain, x0.5 to x	(200)	± 1 %	± 1 %	
ı	Output Range		± 10 V	± 10 V	
ı	Frequency Range(-5 %)	(x0.1 to x99.9 Gain)	0.05 to 100,000 Hz	0.05 to 100,000 Hz	[4]
ı	Frequency Range(-5 %)		0.05 to 50,000 Hz	0.05 to 50,000 Hz	
ı	Phase Response(at 1 kH	Hz)	±1°	±1°	
ı	Cross Talk(maximum)		-72 dB	-72 dB	
ı	TEDS Sensor Support		Yes	Yes	
ı	Fault/Bias Monitor/Meter	r(LED)	Open/Short/Overload	Open/Short/Overload	
ı	Control Interface				
ı	Human Interface		Keypad	Keypad	
ı	Display		2 rows, 16 columns	2 rows, 16 columns	
ı	Digital Control Interface		RS-232	RS-232	
ı	Digital Control: Data Rat		19,200 bps	19,200 bps	
ı	Digital Control: Start, Da		1, 8, 1, No	1, 8, 1, No	
ı	Digital Control: Handsha	•	RTS/CTS	RTS/CTS	
ı	Digital Control: Cable Le	ength(Maximum)	50 ft	15.2 m	
ı	Environmental		.001400.05	0.150.00	
ı	Temperature Range(Op	erating)	+32 to +120 °F	0 to +50 °C	
ı	Electrical	-li-d AC	AC Power	AC Power	
ı	Power Required(for supplemental Power Required(direct in page 2)			DC power	
ı	AC Power(50 to 60 Hz)	iput to unit)	DC power 100 to 240 VAC	100 to 240 VAC	
ı	AC Power (50 to 60 Hz)		1.6 Amps	1.6 Amps	
ı	Excitation Voltage(To Se	ansor)	+24 VDC	+24 VDC	
ı	DC Offset(AC Coupled)	Silgor)	≤ 50 mV	≤ 50 mV	
ı	DC Offset(DC Coupled,	Gain <100)	<10 mV	<10 mV	
ı	DC Offset(DC Coupled,	,	<20 mV	<20 mV	
ı	DC Power	,	+9 to +18 VDC	+9 to +18 VDC	
ı	DC Power		≤ 2.5 Amps	≤ 2.5 Amps	
ı	Constant Current Excitat	tion(To Sensor)	0 to 20 mA	0 to 20 mA	[1]
ı	Output Impedance		≤ 50 Ohm	≤ 50 Ohm	
ı	Overload Threshold(± 0.	.2 Vpk)	+10 Vpk	+10 Vpk	
ı	Clamp Feature	: (4 to 40 000 H) (0 -: 4)	Activated	Activated	[2]
ı	Spectral Noise(1 Hz)(Ga	vise(1 to 10,000 Hz)(Gain x1)	50.0 μV rms 8.0 μV/√Hz	50.0 μV rms 8.0 μV/√Hz	[3] [3]
ı	Spectral Noise(10 Hz)(G		0.0 μV/√Hz 1.5 μV/√Hz	0.0 μV/√Hz 1.5 μV/√Hz	[3]
ı	Spectral Noise(100 Hz)(1.0 μV/√Hz	1.0 μV/√Hz	[3]
ı	Spectral Noise(1 kHz)(G		1.0 μV/√Hz	1.0 μV/√Hz	[3]
ı	Spectral Noise(10 kHz)(1.0 µV/√Hz	1.0 μV/√Hz	[3]
ı		rise(1 to 10,000 Hz)(Gain x10)	75.0 μV rms 20.0 μV/√Hz	75.0 μV rms 20.0 μV/√Hz	[3]
ı	Spectral Noise(1 Hz)(Ga Spectral Noise(10 Hz)(G		20.0 μV/√Hz 1.5 μV/√Hz	20.0 μV/√Hz 1.5 μV/√Hz	[3] [3]
ı	Spectral Noise(100 Hz)(1.0 μV/√Hz	1.0 µV/√Hz	[3]
ı	Spectral Noise(1 kHz)(G		1.0 μV/√Hz	1.0 μV/√Hz	[3]
ı	Spectral Noise(10 kHz)(1.0 μV/√Hz	1.0 μV/√Hz	[3]
ı		ise(1 to 10,000 Hz)(Gain x100)	350 μV rms	350 μV rms	[3]
ı	Spectral Noise(1 Hz)(Ga Spectral Noise(10 Hz)(G		100.0 μV/√Hz 10.0 μV/√Hz	100.0 μV/√Hz 10.0 μV/√Hz	[3] [3]
ı	Spectral Noise(10 Hz)(8.0 μV/√Hz	8.0 μV/√Hz	[3]
ı	Spectral Noise(1 kHz)(G		6.0 μV/√Hz	6.0 μV/√Hz	[3]
ı	Spectral Noise(10 kHz)(6.0 μV/√Hz	6.0 μV/√Hz	[3]
ı	Physical				
	Electrical Connector(ICF		BNC Jack	BNC Jack	
	Electrical Connector(Out		BNC Jack	BNC Jack	
	Electrical Connector(DC	. ,	6-socket mini DIN (female)	,)
	Electrical Connector(RS		DB-9 Connector	DB-9 Connector	
	Size (Height x Width x D	epin)	3.2 in x 8.0 in x 5.9 in	8.1 cm x 20 cm x 15 cm	
	Weight		2.00 lb	908 gm	



All specifications are at room temperature unless otherwise specified. In the interest of constant product improvement, we reserve the right to change specifications without notice. ICP® is a registered trademark of PCB Group, Inc.

OPTIONAL VERSIONS

Optional versions have identical specifications and accessories as listed for the standard model except where noted below. More than one option may be used.

NOTES:

[1]User adjustable, factory set at 4 mA (± 1.0 mA). One control adjusts all channels.

[2]See Manual

[3]Typical, AC Coupled.

[4]0 Hz When DC Coupled [5]See PCB Declaration of Conformance PS024 for details.

SUPPLIED ACCESSORIES:

Model 017AXX Power Cord (1)

Model 100-7103-50 (02711) Multi-conductor cable, 6-ft, 9-pin female to 9-pin male. (1)

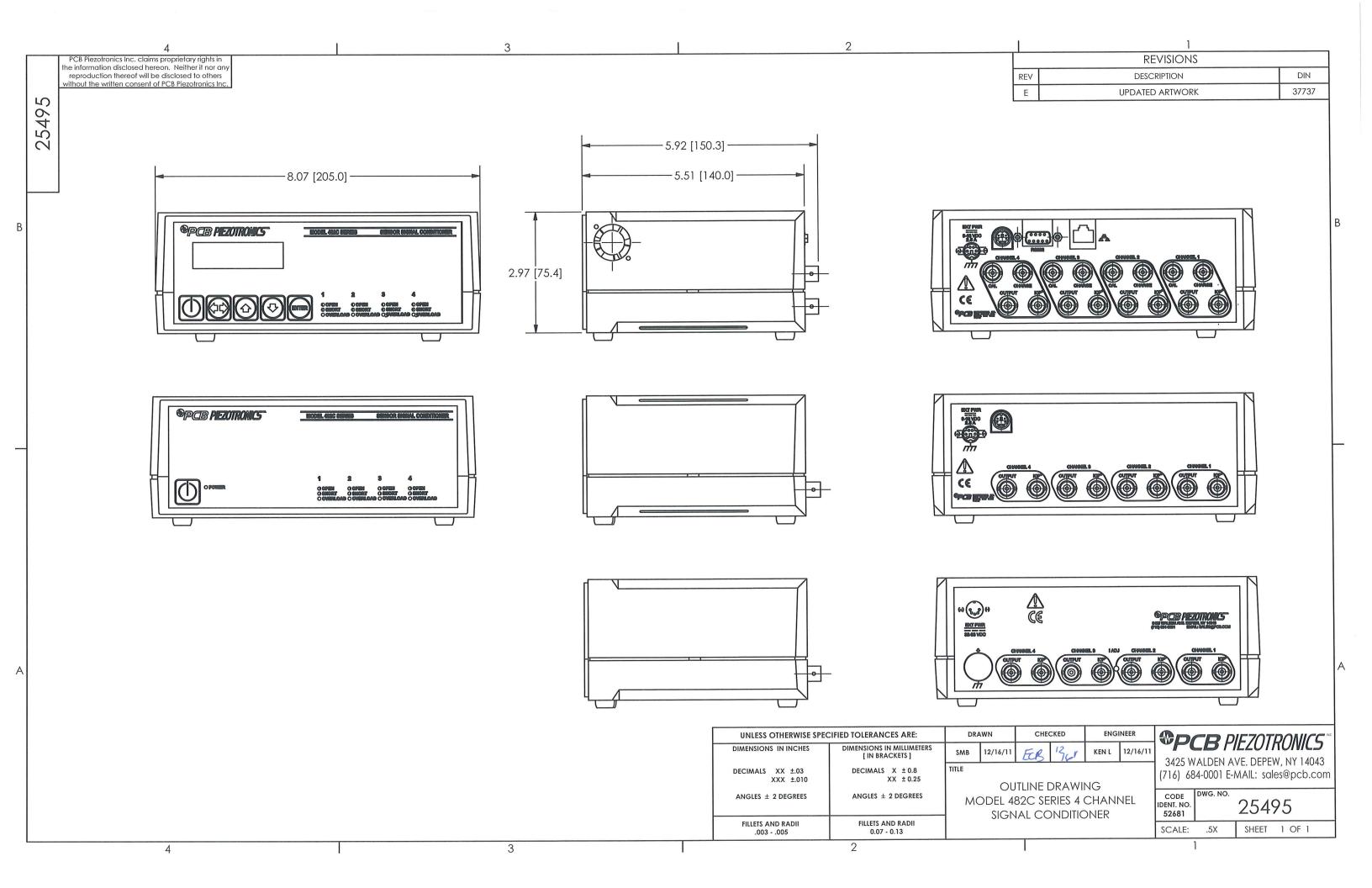
Model 488B14/NC POWER CONVERTOR (1)

Model EE75 PCB MCSC Control Software. (1)

Entered: LK	Engineer: CPH	Sales: ML	Approved: ECB	Spec Number:
Date: 1/20/2016	Date: 1/20/2016	Date: 1/20/2016	Date: 1/20/2016	62808



Phone: 716-684-0001 Fax: 716-684-0987 E-Mail: info@pcb.com



SIGNAL CONDITIONER

Model 482C24

GENERAL OPERATION MANUAL

For powering ICP® sensors and remote charge convertors, this signal conditioner provides an effective method for managing small numbers of sensor channels. A simple command set, entered through industry standard interface, allows the user to generate powerful application-specific programs to automate system testing.

This manual describes the functions and features of model 482C24.

Manual Number:63496 Manual Revision: NR ECO Number: 44778



PCB PIEZOTRONICS, INC. 3425 WALDEN AVENUE DEPEW, NY 14043-2495 PHONE 716-684-0001 FAX 716-684-0987

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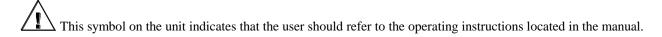
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SEI	NS	26
FS	CI	27
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INP	т	28
IEX	c	28
FL1	rr en	29
OF	LT	29
CLI	MP	29
CP	LG	30
AZZ	ZR	30
VE	xc	30
CA	LB	31
RTI	ED	31
WT	ED	32
ALI	LC	33
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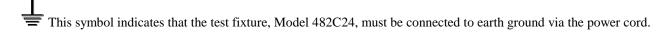
1-0. INTRODUCTION AND SPECIFICATIONS

1-1. Introduction: Safety Considerations WARNING SYMBOLS AND TERMS

The following symbols and terms may be found on the equipment described in this manual.



This symbol on the unit indicates that high voltage may be present. Use standard safety precautions to avoid personal contact with this voltage.



The **WARNING** heading used in this manual explains dangers that might result in personal injury or death. Always read the associated information very carefully before performing the indicated procedure.

The **Caution** heading used in this manual explains hazards that could damage the instrument.

WARNING 1: The power supply/signal conditioner should not be opened by anyone other than qualified service personnel. This product is intended for service by qualified personnel who recognize shock hazards and are familiar with the safety precautions required to avoid injury.

WARNING 2: This equipment is designed with user safety in mind; however, the protection provided by the equipment may be impaired if the equipment is used in a manner not specified by PCB Piezotronics, Inc.

Caution 1: Cables can kill your equipment. High voltage <u>ElectroStatic Discharge</u> (ESD) can damage electrical devices. Similar to a capacitor, a cable can hold a charge caused by triboelectric transfer, such as that which occurs in the following:

- Laying on and moving across a rug.
- Any movement through air.
- The action of rolling out a cable.
- Contact to a non-grounded person

The solution for product safety: 1) Connect the cables only with the AC power off. 2) Temporarily "short" the end of the cable before attaching it to any signal input or output.

Caution 2: ESD considerations should be made prior to performing any internal adjustments on the equipment. Any piece of electronic equipment is vulnerable to ESD when opened for adjustments. Internal adjustments should therefore be done ONLY at an ESD-safe work area. Many products have ESD protection, but the level of protection may be exceeded by extremely high voltage that is typically present in normal situations.

EQUIPMENT RATINGS

For complete specifications, please refer to the enclosed Specification Sheet. This equipment operates optimally at +32 to +120°F (0 to +50°C), in an environment having <85% relative humidity. Its line power frequency range is 50/60 Hz.

482C24 requires 10-15 VDC with 500 mA to operate. In turn, it supplies 24 VDC, 2 to 20 mA excitation voltage to connected ICP® or in-line charge converters sensors. The unit gets its power via AC power adaptor, 12 VDC battery pack, 28 VDC or a car adapter which plugs into the receptacle on the rear panel.

1-2. Model 482C24 System Description

Model 482C24 is a four-channel, bench top signal conditioner designed to interface measurement signals to readout or recording devices. The unit provides 1 to 20 mA of constant current excitation to power ICP® sensors and in-line charge converters. Other features include incremental gain, AC/DC coupling, front panel keypad/display and the ability to read and write TEDS (transducer electronic datasheet).

List of 482C24 features:

- ICP® and Voltage sensor input
- AC/DC coupling selectable per channel
- Auto zero function that negates DC bias
- Clamped output selectable per channel
- Incremental gain, x0.1 − x200
- Front panel keypad and display
- Capable of reading/writing binary data from/to TEDS devices
- RS-232 interface for computer control with supplied MCSC software
- 12-bit accuracy signal conditioning
- Input fault and overload LED
- Variable ICP[®] source current, 0 to 20 mA per channel
- Illuminator lights and a power button on the front panel
- Rear panel BNC input/output connectors
- Non-Volatile Memory

1-2.1 Model 482C24 ICP® Input/ Output Mode

482C24 contains a regulated 24 VDC power supply that provides constant current for up to 4 individual channels. Both the output and input connections utilize BNC connectors and are brought out through the rear panel.

1-3. Block Diagram

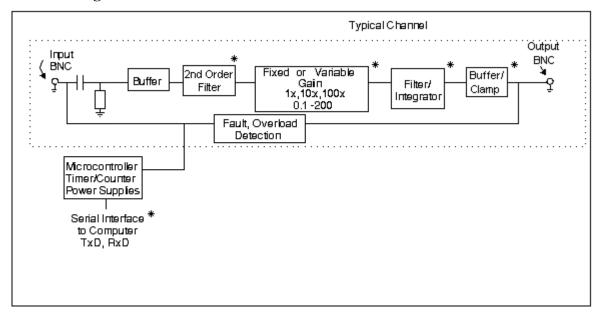


Figure 1 Generic block diagram of model series 482C signal conditioners (* = option)

1-4 Installation

Model 482C24 comes in the form of a standard box. The box should be located in such a way as to allow convenient access to the power outlet for disconnect purposes. Since these units have low power consumption, they can be located in confined environments.

1-4.1. Grounding Techniques

Integrating model 482C24 unit into an application that links the outputs to other test equipment powered by line voltages may lead to errors or loss of signal-to-noise ratio due to ground loops. The evidence of ground loops is easily seen whenever the fundamental frequency (50 or 60 Hz) or a multiple of the fundamental frequency is present in the system when the sensors are "at rest." In order to maintain the operating specification of noise and reduce the effects of line interference, proper grounding techniques should be used. The following procedure may be helpful:

- 1. Make sure the signal ground lines of all equipment are tied together. The signal grounds of the channels are typically tied together via the case of the input and output BNC connectors. The individual channels of 482C24 have their signal ground line tied together internally at the power supply.
- 2. Insure that the sensor does not pick up line noise from the body under test. The case of the sensor should be isolated from the body under test (ground) using an isolation pad. The isolation pad breaks the loop formed by the signal path of the sensor to the 482C24 and the return (ground) from 482C24 back to the sensor.
- 3. Make sure that all equipment signal grounds of the test system are tied to the Earth ground at a single point and the connections linking the equipment ground are made using a wire that can provide a very low impedance connection.

1-4.2 Quick Set-up Instructions

1-4.2a Front Panel Introduction

The following illustration shows the front panel module as it appears on the Model 482C24 when initially powered on.

PCB 482C24

FW Vnnn.n



- This button is used to scroll DOWN through the options in the menus. In the submenus, this button can be used to change the channel and increments.
- This button is used to scroll UP through the options in the menus. In the submenus, this button can be used to change the channel and increments.
- This button moves you in the left / right direction through the menus and submenus.

ENTER: This button applies the setting of the option just set, while exiting the user out of the submenu.

Note: Please refer to section 1-4.1b and 1-4.2c for instructions on how to set the mode and gain options. The settings for these options should be considered before unit is used to collect data

Note: In the submenus a flashing cursor represents a menu that will accept user input. A non-flashing cursor represents a status menu, no input needed.

1-4.2b Mode Option

Model 482C24 includes two input modes – ICP[®] and Voltage. The factory default for all channels is ICP[®]. To change the mode select the INPT option from the main menu use the down \downarrow arrow button to scroll down and the left / right \longleftrightarrow button until the cursor is over INPT and the hit ENTER.

Gain	Sens	INPT
FSOT	FSIN	FLTi

A submenu will appear. Choose the channel you wish to change by using the up \uparrow or down \downarrow arrows. Once that is done use the left / right \longleftrightarrow button to move the cursor over to the Input Type column. To change the mode, use either the up \uparrow or down \downarrow arrow to scroll through the options. You can set the channel to be in either ICP® or voltage mode. Once you have it set, you can either scroll back to the channel column; to change the mode on another channel; or hit ENTER to save the changes.

Example: If you want to change channel 2 to be in Voltage mode you would perform the following steps:

Scroll and select INPT from the main menu, and hit enter. Once in the submenu, the flashing cursor will be in the channel column, hit the up \uparrow arrow button until the channel column reads 2

Chan	Input Type
2	ICP

Hit the left / right \longleftrightarrow arrow key once so that the cursor is over the Mode column. Use the up \uparrow or down \downarrow arrow keys until the mode says Voltage.

Chan	Input Type
2	VOLTAGE

Once you have hit enter, your changes will be saved.

NOTE: To make a global change (set all the channels to the same mode) set the channel to ALL.

1-4.2c Programmable Gain Option

To enter the submenu for the variable gain option, place the cursor over the word "Gain" in the main menu. This is shown as:

Gain	Sens	INPT
FSOT	FSIN	FLTi

By pressing the ENTER button, the submenu for changing the gain of any channel appears on the display. The submenu pertaining to the "Gain" selection appears as:

Channel	Gain
1	001.0

Example: To set the gain of Channel 2 to x10, perform the following steps:

The flashing cursor appears over the channel selection. Choose the channel you wish to change by using the up \uparrow or \downarrow arrows. Once you have selected the channel, use the left/right \longleftrightarrow arrow key to move the flashing cursor over to the gain column.

Channel	Gain
2	001.0

To change the gain, use the up \uparrow and down \downarrow arrow keys to scroll through the values. Model 482C24 has incremental gain selectable from .1 to 200.0. Use the left/right \longleftrightarrow arrow key to move the flashing cursor over any digit in the gain column to select an appropriate value.

In this example, a gain of 10 is selected; (see example below). As with all setting changes, the actual gain internal to the unit is changed when the 'ENTER' button is pushed.

Channel	Gain
2	010.0

To set the next channel, press the left right \longleftrightarrow arrow key to resume channel control, then press the up \uparrow or down \downarrow arrow keys to select a different channel. Continue making selections with the directional keys until all desired channels are set, then press the ENTER key to return to the option menu.

Note: To make a global change (set all the channels to the same gain) set the channel to ALL.

1-5. Operation: Standard AC Line

Plug the adapter into any 100 - 240 VAC 47 - 63 Hz power source, attach the supplied ferrite clamp on the AC cord to ensure CE conformance. The ferrite clamp should be placed as close to the signal conditioner as possible. Press the "ON/OFF" button to turn the unit on.

1-5.1 Using the Power Adapter

When using a power adapter to power the unit, make sure to observe the correct pin out, as indicated on the rear panel of the unit.

CAUTION: Refer to the rear panel for proper input voltage and currents.

1-6. Maintenance and Repair

It is not recommended that the customer attempt repair of the Model 482C in the field. Should trouble occur, contact the factory for assistance. If the unit becomes dusty and dirty, it may be wiped off with a soft cloth.

2-0 FRONT PANEL MODULE CONTROL

2-1 Introduction

Model 482C24 is equipped with the capability of controlling functions through the front panel module. This module consists of a display and five (5) push buttons. The display shows various menus in which all of the available options are given. The user may scroll through the menu, and choose any option to change the settings.

2-2 Unit Initialization

Upon pressing the ON/OFF button, the unit will turn on and display the following:

PCB 482C24 FW Vnnn.n

The unit is initialized, with the factory default settings.

The factory defaults are:

- Gain = 1.0
- Sensitivity = 10.0
- Full Scale input = 1000.0
- Full Scale output = 10.0
- Input Mode = ICP
- Input Filter = Disabled
- Current excitation = 4.0 mA
- Output Filter = Disabled
- Coupling = AC
- Clamp = OFF

2-3 Main Menu Format

Initially, pressing any button will cause the first two menu lines to be displayed and the cursor will blink on the 'Gain' option.

GAIN SENS INPT FSOT FSIN FLTi

The cursor may be moved around the main menu by using the arrow keys. To show the other selections of the main menu, press the down \downarrow or up \uparrow arrow key. This action scrolls vertically to the subsequent lines on the menu. The additional menu lines that can be selected from are shown below.

EXCi	EXCv	FLTo
ACDC	ZERO	ARNG
SWOT	CLMP	Bias
CHRD	Cal	LEDS
Ver?	Unit	Reset
Disp	Savs	Res

2-4 Submenu Format and Command Selections

1) Gain Options:

The 482C24 includes the incremental gain which provides has the ability to automatically adjust the gain of each channel based on three other channel values. These values are; the Sensitivity of the sensor, the Full Scale value of the input (FSI) in engineering units (g's for instance), and the Full Scale Output (FSO) of the amplifier expressed in Volts (this is the output that a signal at an FSI level will produce). The amplifier will always force the gain equation to be true by adjusting either the gain, if one of FSI, FSO or SENS changes, or FSI if the Gain is set directly. The Gain equation is as follows:

Gain = (FSO *1000) / (FSI*SENS)

Gain Limits:

The 482C24 ICP® & Voltage input modes have a maximum gain of 200.

Setting the Gain:

To enter the submenu for the variable gain option, place the cursor over the word "GAIN" in the main menu. This is shown as:

GainSENSINPTFSOTFSINFLTi

By pressing the ENTER button, the submenu for changing the gain of any channel appears on the display. The submenu pertaining to the "Gain" selection appears as:

Channel	Gain
1	0001.0

The flashing cursor appears over the channel selection. Choose the channel you wish to change by using the up \uparrow or \downarrow arrows. Once you have selected the channel, use the left/right \longleftrightarrow arrow key to move the flashing cursor over to the gain column.

To change the gain, use the up \uparrow and down \downarrow arrow keys to scroll through the options. Model 482C24 has incremental gain selectable from .1 to 200.0. Use the left/right \longleftrightarrow arrow key to move the flashing cursor over any digit in the gain column to select an appropriate value. The actual gain internal to the unit is changed when the 'ENTER' button is pushed.

To set the next channel, press the left/right $\leftarrow \rightarrow$ arrow key to resume channel control, then press the up \uparrow or down \downarrow arrow key to select a different channel. Continue making selections with the directional keys until all desired channels are set, then press the ENTER key to apply the settings and return to the option menu.

NOTE: To do a global change (set all the channels to the same gain) set the channel to ALL.

2) Sensitivity Value:

Entering a Sensitivity value will cause the gain of the unit to be changed based on the equation shown above. Sensitivity is set in the same way that the incremental gain value is set, using the left/right \longleftrightarrow arrow key to move the flashing cursor over any digit in the SENS column to select an appropriate value. As with all setting changes, the actual gain internal to the unit is changed when the 'ENTER' button is pushed.

GAIN	Sens	INPT
FSOT	FSIN	FLTi

The sub-menu of the "SENS" selection shows the current value for sensor sensitivity (assumed to be mV/EU):

Channel	SENS
2	00100.000

3) Full Scale Input Value:

Entering a Full Scale Input value will cause the gain of the unit to be changed based on the gain equation shown previously. The FSI value is set in the same way that the incremental gain value is set, using the left/right \longleftrightarrow arrow key to move the flashing cursor over any digit in the FSIN column to select an appropriate value. As with all setting changes, the actual gain internal to the unit is changed when the 'ENTER' button is pushed.

GAIN	SENS	INPT
FSOT	FSIN	FLTi

The sub-menu of the "FSIN" selection shows the current value for Full Scale Input (assumed to be EU):

Channel	FS_IN
2	01000.000

4) Full Scale Output Value:

Entering a Full Scale Output value will cause the gain of the unit to be changed based on the equation shown previously. The FSO value is set in the same way that the incremental gain value is set, using the left/right \longleftrightarrow arrow key to move the flashing cursor over any digit in the FSOT column to select an appropriate value. As with all setting changes, the actual gain internal to the unit is changed when the 'ENTER' button is pushed.

GAIN	SENS	INPT
FSOT	FSIN	FLTi

The sub-menu of the "FSOT" selection shows the current value for Full Scale Output in Volts. The range is 0.5 to 10.0

Channel	FSOT
2	10.0

5) Input Modes:

The 482C24 allows the user to switch between ICP[®] and Voltage input modes. The factory default for all channels is ICP[®]. To change the mode select the INPT option from the main menu using the left / right \longleftrightarrow arrow keys until the cursor is over the INPT option, and then press the Enter button.

Gain	SENS	INPT
FSOT	FSOT	FLTi

The following submenu will appear. Choose the channel you wish to change by using the up \uparrow and down \downarrow arrow keys. Next, use the left / right \longleftrightarrow arrow key to move the flashing cursor over to the Mode column. To change the INPT, use either the up \uparrow or down \downarrow arrow key to scroll through the options, once you have the desired setting selected hit ENTER to apply it.

Chan	INPUT TYPE
2	ICP

NOTE: Setting a channel to Voltage Input will cause the ICP[®] current source for that channel to be turned off. Conversely, If ICP[®] is set from Voltage mode then the ICP[®] current source will be set to 4mA.

6) Input filter option (not Standard on 482C24, contact the factory for options):

Each channel's input filter setting can be set independently of the other channels. To change the Input Filter setting from the main menu, use the left / right \longleftrightarrow arrow keys until the cursor is over the FLTi option, and then press the Enter button.

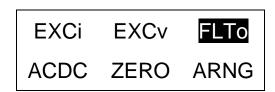
GAIN SENS INPT FSOT FSIN **FLT**

The following submenu will appear. Choose the channel you wish to change by using the up \uparrow and down \downarrow arrow keys. Next, use the left / right \longleftrightarrow arrow key to move the flashing cursor over to the INP Filter column. To change the Filter setting, use either the up \uparrow or down \downarrow arrow key to select either 'On' or 'Off', once you have the desired setting selected hit ENTER to apply it.

Chan	INP Filter
2	Off

7) Output filter option (not Standard on 482C24, contact the factory for options):

Each channel's output filter setting can also be set independently of the other channels. To change the Output Filter setting from the main menu, use the left / right \longleftrightarrow arrow keys until the cursor is over the FLTo option, and then press the Enter button.



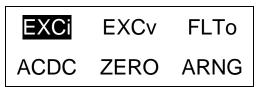
The following submenu will appear. Choose the channel you wish to change by using the up \uparrow and down \downarrow arrow keys. Next, use the left / right \longleftrightarrow arrow key to move the flashing cursor over to the Out Filter column. To change the Filter setting, use either the up \uparrow or down \downarrow arrow key to select either 'On-nn.nk' or 'Off', once you have the desired setting selected hit ENTER to apply it.

Note: the ON setting also indicates the filter corner, in kHz, implemented by the filter for the channel.

Chan	Out Filter
2	ON-10.0k

8) ICP® Current Adjustment:

The current excitation value can be set from 0 - 20 mA. Where 0 = Off. To set the current excitation value, move the cursor to the 'EXCi' location, as shown below.



Pressing the ENTER button, will cause the following submenu to appear. The ICP[®] current may be altered by using the up \uparrow or down \downarrow arrow keys.

Chan	ICP Current
4	02 mA

The 482C24 will turn off the current excitation signal if the unit is not in ICP^{\circledast} input mode and will not allow it to be set unless it is in ICP^{\circledast} mode. If a channel is selected from the Iexc menu that is inappropriate then **NA** will appear as shown below in place of the ICP^{\circledast} current settings. Also, because of this limitation, the 'ALL' channel selection is not allowed for this setting.

Chan	ICP Current
2	NA

NOTE: The factory default setting for the ICP[®] current is 4 mA.

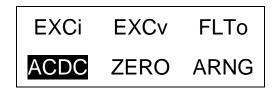
9) Voltage Excitation:

Voltage excitation is not applicable to the 482C24. The 'Option Not Installed' message will appear if it is activated.



10) Input Coupling:

482C24 includes AC/DC coupling selectable per channel. The AC coupled mode passes the signal through a DC blocking capacitor or high pass filter to remove the sensor bias voltage. By moving the cursor on the ACDC location, the display shows:



When the ENTER button is pressed, the submenu for the coupling options will include; **AC**, **DC**. The selection can be changed by using the up \uparrow or down \downarrow buttons.

Chan	Coupling
1	DC

The coupling options are AC or DC. In DC coupling mode the Auto Zero function becomes available.

11) Auto Zero/Auto Balance:

Model 482C24 provides a function for automatically zeroing the channel output for any input type in DC coupling mode. This function is not available when the channel is AC coupled. The Zero function disconnects the input and uses a DAC to reduce the channel output to close to 0V.



When the ENTER button is pressed, the submenu for the Zero options will include; **Cancel, AUTOBAL, AUTOZERO**. The selection can be changed by using the up \uparrow or down \downarrow buttons.

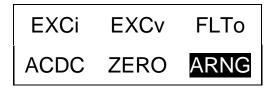
Note: The Auto Balance function (AUTOBAL) is not applicable to the 482C24. It is a bridge input mode function which is not supported on the 482C24. If selected an Input Mode error message will be displayed.

Chan	AUTOZERO
1	AUTOZERO

Note: If the zero function fails the message "Error Removing MainBd DC Offset" may be displayed. The function tries to get the output level below 2mV for the 482C24.

12) Auto-Range:

The auto-range (also referred to as auto-scale) feature provides an automatic scaling of the output signal. Please refer to section 3-7.1 for further description. With this command, the programmable gain is implemented to give 0.8 of the Full Scale Output. The signals are checked internally using the onboard A/D. To use this feature, place the cursor over the word "ARNG" on the display and press the enter key, the following submenu will appear.



Use the up ↑ or down ↓ arrow keys to toggle between the 'OFF', 'ON', or 'IMED' options. Once you have set the Autoscale option, hit the ENTER key to return to the main menu. ON turns the auto scale function ON and it will continue scaling the gain until it is manually turned off. The 'IMED' option runs through the auto-scale algorithm once and then turns it off automatically.

Chan	Autoscale
2	Off

Note: Auto-scale option should NOT be left on while measurements are being taken. It is strictly to be used during the setting of the gain, and then the option should be turned off.

13) Switched Output:

Switched Output is not applicable to the 482C24. The 'This Option is Not Installed' message will appear if it is activated.

SWOT	CLMP	Bias
CHRD	Cal	LEDS

14) Clamp:

482C24 includes a clamped output that is selectable per channel. It is selected by pressing the ENTER key on the front panel when the cursor is located on the CLMP option.

SWOT	CLMP	Bias
CHRD	Cal	LEDS

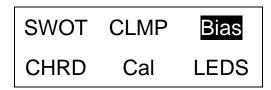
The following submenu will appear. Choose the channel you wish to change by using the up \uparrow and down \downarrow arrow keys. Next, use the left / right \longleftrightarrow arrow key to move the flashing cursor over to the CLMP column. To change the clamp setting, use either the up \uparrow or down \downarrow arrow key to select either 'On' or 'Off', once you have the desired setting selected hit ENTER to apply it.

Chan	Clamp
1	On

Note: When Clamped, the conditioner is internally set to automatically keep pulsating output signals ground based (within 20mV negative undershoot) and positively poled. This clamp is useful in stabilizing output signals when interfacing with instrumentation that requires repetitive pulse train signals be ground based and of one polarity (usually positive). When the output signal is not clamped, a repetitive pulse train will gradually drift downward and stabilize in time with equal areas above and below signal ground.

15) Bias Measurement:

482C24 is capable of measuring the bias voltage present on each of its channels. By moving the cursor upon the "Bias" location, the display appears as follows:



Using the ENTER button, the submenu appears as shown in the following diagram. Choose the channel you wish to change by using the up \uparrow and down \downarrow arrow keys. The bias reading for the channel will be displayed automatically when the channel is selected.

Chan	Bias
2	0023.7

If unit had a short circuit, the bias voltage would be <2.0V. Proper bias voltage is between 2.0V and 22V. Anything over 22V would indicate an open circuit.

16) Channel Output Measurement:

The 482C24 is capable of digitizing the channel output and displaying it on the front panel. By moving the cursor upon the "CHRD" location, the display appears as follows:

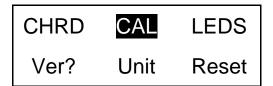
SWOT	CLMP	Bias
CHRD	CAL	LEDS

Using the ENTER button, the submenu appears as shown in the following diagram. Choose the channel you wish to change by using the up \uparrow and down \downarrow arrow keys. The output reading for the channel will be displayed automatically when the channel is selected.

Chan	Output
1	005.3

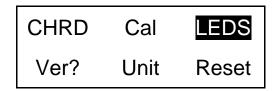
17) Calibration:

The Cal option is not applicable to the 482C24. The 'This Option is Not Installed' message will appear if it is activated.



18) LED Test:

The testing of the front panel LEDs allows you to check whether or not they are functioning properly. To test them, place the cursor over the word "LEDS" on the display and press enter.



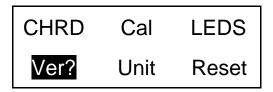
The screen shown below will be displayed:



Use the up or down arrow key to select 'Execute' or 'Cancel'. Both options return control to the main menu. If 'Execute' is selected then the LED's will blink 3 times if 'Cancel' is selected then no action is taken.

19) Firmware Version:

To determine the firmware version of the unit select the 'Ver?' menu option and hit enter.

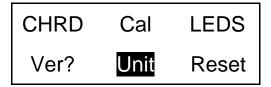


A screen similar to the one shown below will be displayed:

PCB 482C24 FW v4A2.5

20) Unit ID:

The Unit ID may be changed by pressing the ENTER key on the front panel when the cursor is located on the Unit option.



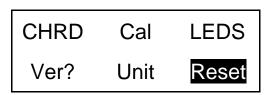
The following submenu will appear. Use the up \uparrow or down \downarrow arrow key to change the Unit Id setting to a new value. Once you have the desired setting selected hit ENTER to apply it.

Current Unit #

Note: Changing the Unit ID is only necessary if you have the Ethernet or RS-232 communication option installed and you are communicating with more than one unit. If this is the case then all units in the network MUST have a unique ID. Model 482C24 includes an RS-232 port.

21) Reset to Factory Default Settings:

The 482C24 reset capability provides a mechanism to reset the unit to its factory default settings. To do this select the Reset option from the menu by placing the cursor over the Reset option and hitting enter.

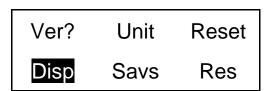


Pressing the ENTER brings up a submenu that allows the operator to continue by selecting 'Execute' or cancel the function by selecting 'Cancel'. Both options return control to the main menu. If 'Execute' is selected then the defaults are restored.

Factory Defaults
Execute

22) Display Content Options:

The Display option allows the user to choose from 3 selections of front panel content. To enter this mode, place the cursor over the Disp option and hit enter.



Pressing the ENTER brings up a submenu that allows the operator to continue by selecting either 'Gain', 'Bias' or 'Output'. If 'Gain' is selected then each channel's current Gain setting will be displayed on the 2^{nd} line of the front panel display to the nearest integer. If the gain is greater than two significant digits then it is displayed in terms of thousands (i.e. 100 = 0.1k, 200 = 0.2k). Additionally, directly above the Gain on the 1^{st} line of the display will be up to 3 characters representing the channels input mode; '1' for $ICP^{\textcircled{@}}$, or 'V' for Voltage. Next to the Input mode indicator is the Input Filter setting; '*' for On, blank for Off and '-' if the option is not installed. Next to the Input Filter indicator is the Output Filter setting indication which has the same markings as the input filter.

Display Opts Gain

Following is what the screen will look like if the Display was set to show 'Gain' and channel 1 has a gain of 100 and is in ICP® mode with the input filter 'On' with no Output Filter option installed. Similarly, channel 2 has a gain of 200 and is in ICP® mode with the input filter off; channel 3 has a gain of 1 and is in Voltage mode with an input filter enabled and channel 4 has a gain of 10 and is in Voltage mode with the input filter off.

I*- I - V*- V -0.1k 0.2k 1 10

The 'Bias' display option is the same as the Gain option except the channels bias reading replaces the Gain setting. Also the Bias reading will be refreshed periodically.

Following is what the screen will look like if the Display was set to show 'Bias'.

I*- I - V*- V -B14 B14 B24 B24

The 'Output" display option is the same as the Bias option except the channels Output is digitized and displayed. As with the Bias reading it will be refreshed periodically.

Following is what the screen will look like if the Display was set to show 'Output'.

Note: Due to the limited screen size values less than or equal to -9.9 are displayed as -9.9 and values greater than or equal 9.9 are displayed as 9.9.

23) Save Current Setting:

Activation of 'Savs' causes the current settings to be saved as the default settings and used when the unit is powered up again. This command is useful for units without an on/off power button. For units with a power button the settings are automatically saved when the unit is powered down using the button.



24) Reserved:

No operation. These menu items are reserved for future use.



Reference

3-0. THEORY OF OPERATION

3-1. Sensor Excitation

ICP[®] refers to a low output impedance voltage mode sensor combining an integrated circuit and a piezoelectric sensing element in a single housing to provide a voltage output. This sensor is powered by a +24 VDC power supply having a constant current, variable from 2 to 20 mA.

Sensor excitation occurs as the constant current of all channels are set. Model 482C24 allows the constant current to be adjusted between 0 and 20 mA to provide the required excitation for most applications. Special situations, such as driving extra-long cables (more than 1000 ft) with high frequency or fast rise time pulses, may require increasing the drive current to 12 mA or higher.

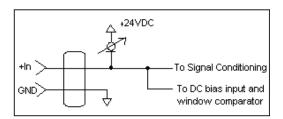


Figure 2 ICP® Sensor Excitation

When driving fast rise time pulses over long lines, system performances can be optimized by "tuning" the drive current to the line; i.e. by finding the best current setting for the particular test of physical parameters. To determine the optimal current setting, experiment with your particular test set up. To insure optimal accuracy in constant-current adjustment, make sure all channels have sensors or simulated loads, similar to the one provided by model 401B04 sensor simulator, consisting of a voltage amplifier similar to those found in ICP® sensors.

3-2. Input Protection

The input section has protection to limit the amplitude of the incoming signal to within +24 volts to ground. Maximum allowable input voltage without distortion is ± 10 volts, relative to the sensor bias voltage.

3-3. Input Fault Detection

Model 482C24 monitors two input fault conditions, "short" and "open," which indicate problems with sensor input and is displayed through the front panel LEDs. Either case implies that the sensor is NOT functioning properly. An input is **shorted** when it has a ground path for the sensor excitation and **open** when the sensor fails to draw the excitation.

Two voltage comparators consist of a window comparator that has two reference voltages (V_{ref}) representing thresholds for "short" and "open." When the sensor's bias voltage (V_{bias}) exceeds the comparator range, the front panel input fault LED lights.

Note: Red LED implies input fault.

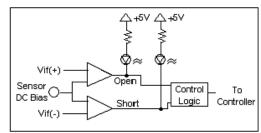


Figure 3 Input Fault Window Comparator with LED Indicator

3-4. Input Interface

The input signal conditioning for each channel provides a unity gain buffer with high-input impedance amplifiers. With the AC coupled option it also eliminates the DC bias from the input signal with a 10-second time constant.

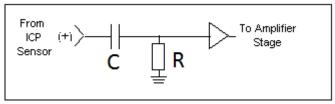


Figure 4 Input Amplifier Configuration

3-5. **Gain**

The Programmable Gain Amplification (PGA) block consists of a decimal gain amplifier. See Figure 3-5.1.

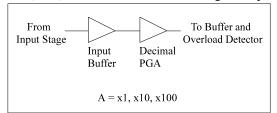


Figure 5 Selectable Gain Amplifier Configuration

3-5.1 Programmable Gain

With programmable gain the user can adjust the gain as needed. Incremental is available gain on the 482C24 from 0.1 to 200. The incremental gain step is 0.1. Incremental gain is particularly useful in the standardization of groups of sensors. Consider the following example, wherein the user desires to normalize sensitivities to 1 V/unit for each channel.

Channel	Sensor Sensitivity	Gain Setting of 482C	Actual Gain Needed
1 st	$10.10^{\text{ mV}}/_{\text{unit}}$	99.00	99.01
2^{nd}	$101.32 \mathrm{^{mV}}/\mathrm{_{unit}}$	9.9	9.869
$3^{\rm rd}$	$22.30^{\text{ mV}}/_{\text{unit}}$	44.8	44.84

These results may be accomplished by using either of two techniques. First, the user may set the gain via the computer interface command set (See the command strings in Section 4-9 in the Computer Interface Programming Guide) or the user may set the gain by using the front panel control.

3-6. Normalized Output Sensitivity

The definition of normalized output sensitivity is the calculation of the individual channel's gain, depending on the sensitivity of the sensor attached and the desired output sensitivity. This is simply a function of the desired output sensitivity (in Volts/ unit) divided by the sensor's sensitivity.

Additionally, a feature to improve flexibility allows changing the output level to a value of 5 Volts/ unit instead of normalized 1 Volt/ unit. Some users request the ability calculate the gain using a known input signal along with the sensor sensitivity, and desired output level. The result of the request impacts the formula:

$$Gain = {^{1\;Volt/}} / _{[Sensitivity\;(mV/unit)\;*\;Full\;Scale\;Input\;(units)]}$$

Adding some simple error checking to insure the limits of the sensor and gain limits of the signal conditioner are not exceeded completes the normalization process.

$$Gain_{normalized} = {}^{FSOT (V)} / {}_{SENS * FSIN}$$

Additional Considerations:

The storage of individual channel gains is stored in non-volatile memory locations. The new variables for each channel's sensitivity, Full Scale Output level, and Full Scale Input are stored in non-volatile memory locations when the unit is powered down.

The error checking should provide a flag if the desired normalized output level is not feasible due to gain limitations. The gain required may be too large given the sensor sensitivity defined, or too small which implies the sensor will not be capable measure the expected value. The typical sensor will output a signal up to ± 5 Volts. The maximum swing may be used in the error checking.

3.7 Auto scaling and Overload Detection

3-7.1 Auto scaling

To avoid overload, model 482C24 features auto scaling for gain adjustment. It first sets maximum gain on all channels, then decreases the gain setting of any channel on which an overload has occurred. The gain auto scale continues until there is no overload with respect to the preset overload threshold level (standard ± 10 volts) and sensed signal of the

channel. Final gain and overload status interrogation is possible through the command set. The correct procedure for using the auto scale feature is as follows:

- 1. Excite the structure under test.
- 2. Enable auto scale (Auto scale on).
- 3. Wait several seconds, until the unit is stabilized.
- 4. Disable auto scale (Auto scale off).
- 5. Read the gains of all channels.
- 6. Begin test run.

3-7.2 Overload

The overload feature uses the same window comparator principle previously discussed. The $+V_{ref}$ is equal to the default overload value of ± 10 volts. When the input voltage (Vsignal of Figure 3-7.1) to the window comparator exceeds the reference voltage limits, overload has occurred, and the comparator's output, which is normally "high," becomes "low." This "low" state illuminates the overload LED and triggers the latch of overload detection circuitry. During regular measuring time, the latch holds the occurrence of overloads until the user reads its status through the computer interface.

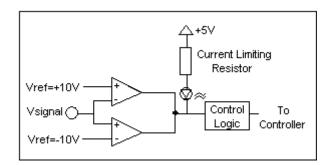


Figure 6 Auto scale/Overload Window Comparator

3-8. Connector Configuration

482C24 provides BNC inputs and outputs for ICP®-type sensors.

Input/ Output Connector Definitions:

The BNC connectors are used to accept ICP® and Voltage mode input signals. The ICP® excitation will be present on the input BNC only when the ICP® current is turned on. The voltage input mode allows bipolar, positive and negative (above and below ground) signals. In all input modes, the signal must be AC type signals, unless the DC coupling option is turned on.

3-9. RS-232 Interface

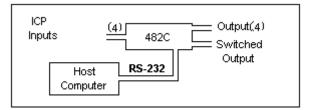


Figure 7 RS-232 Configuration

The RS-232 Interface provides serial control of 482C24. This may be accomplished through the use of a personal computer, dumb terminal, or handheld controller. The command format is based upon letter representations of the controllable options. This serial interface, set-up, and programming are described in Section 4.

3-10 Non-Volatile Memory

This feature keeps the programmed configurations stored when the unit is powered down. When the unit is turned on, all programmable features (e.g., gains, input mode) active at last use are preserved. When the unit is powered down the non-volatile memory is updated with the current channel settings. The unit's non-volatile memory may be reset to the factory default settings by using the reset menu option.

3-11 Transducer Electronic Data Sheet (TEDS) Interface

The TEDS sensors attach to the input connectors the same way a traditional ICP® sensor is attached to the 482C24. The TEDS interface requires both the RS-232 or Ethernet computer interface option, and the input mode option. The digital control and input mode features automatically perform the TEDS read or write function. After the communication with the TEDS sensor is complete the input mode returns to the input mode (charge or ICP®) prior to the communication.

The current TEDS function will perform a read of the "raw" TEDS data and return the 32 bytes of TEDS sensor EEPROM data and the 8 byte Application register contents, if it was programmed, and returns the data in an ASCII Hex representation. This raw data may be decoded using PCB's Multi-Channel signal conditioner software (PN EE75).

4-0. COMPUTER INTERFACE PROGRAMMING GUIDE

For RS-232 or Ethernet equipped units (482C24 includes an RS-232 interface)

4-1. Introduction

Individual commands are subject to feature availability on the particular unit. The RS-232 Interface enables the 482C24to be fully controlled by a computer or handheld controller. With this interface, the unit is able to become part of a fully automated system.

4-2 RS-232

The RS-232 provides total control of the unit except for hardware RESET. The rest of the options described previously are computer-controllable.

4-3. RS-232 Host Set-Up

Before any serial interface is used to communicate with the host computer, a specific set-up must be followed. These parameters must be set for the host computer. The full list of parameters is shown below: (EOL = End of Line.)

Parameter	Setting
Transmission Rate	19,200 BPS (bits per second)
Parity	None
Number of data bits	8
Number of stop bits	1
Handshaking	None
Echo	None
Transmit EOL	Carriage Return and Line Feed, <cr><lf></lf></cr>
Receive EOL	Carriage Return and Line Feed, <cr><lf></lf></cr>

4-4. RS-232 Rear Panel Pin out Listing

Number of 9-Pin Connector	Function	Notes
1	N.C.	Not Connected
2	TXD	From 482C
3	RXD	To 482C
4	N.C.	Not Connected
5	Ground	Ground
6	N.C.	Not Connected
7	N.C.	Not Connected
8	N.C.	Not Connected
9	N.C.	Not Connected

4-5. Ethernet Communication

The 482C24 does not provide Ethernet communication.

4-6. Model 482C24 Communication Guidelines

1) Data transfer from the host terminal to the unit must contain an ending delimiter of <CR><LF>.

Example: <CR><LF> -Carriage Return and Line feed. (In ASCII, <CR> is 13; <LF> is 10.)

- 2) The number of characters for any command string, from the first character to the <CR>, may not exceed 255.
- 3) Status request commands, i.e., commands ending with a "?", may only be sent within one transmission.

Example: 7:0:GAIN?<CR> <LF>

-Reads the gain setting of all channels.

4-7. Model 482C24 Unit Initialization Procedure

- 1) To begin, plug 9-pin female DSUB connector of given cable into RS-232 port of model 482C24. Plug the other end of the cable into the COM port of the computer.
- 2) Turn on power to the unit. The display or power indicator should light up to indicate the power is on.
- 3) With a computer that is set up to transmit data, according to the host set-up discussed in Section 3-3, send the command:

This command flashes the front panel LEDs three times.

4-8. Command Summary

The table below is a summary of the 482C24 command set. The 482C series is highly differentiated and some commands may not be valid in all units. The 482C commands are sent and received from/to the host computer in ASCII text format.

Command	Type	Scope	Meaning
GAIN	R/W	Channel	Set or read gain
SENS	R/W	Channel	Sensor Sensitivity
FSCI	R/W	Channel	Expected Full Scale Input Value

FSCO	R/W	Channel	Full Scale Output
INPT	R/W	Channel	Input Signal Mode Selection
IEXC	R/W	Channel	Read/Adjust ICP® current setting
FLTR	R/W	Channel	Enable/disable input filters
OFLT	R/W	Channel	Enable/disable output filters
CLMP	R/W	Channel	Enable/disable Clamp
CPLG	R/W	Channel	Select AC or DC coupling
CALB	R/W	Channel	Select Internal or External Cal setting
SWOT	R/W	Unit	Switched output (4 to 1 mux)
RTED	R	Channel	Read binary TEDS data from a sensor
WTED	W	Channel	Write binary TEDS data to a sensor
ALLC	R	Channel	Read most channel settings
RBIA	R	Unit	Measure Bias (returns all channels)
STUS	R	Unit	input fault / overload status, for all channels
UNIT	R	Unit	Read Unit Configuration information
CHRD	R	Unit	Read Channel output (returns all channels)
UNID	R/W	Unit	Set Unit ID
LEDS	FCN	Unit	Front panel LED test function
RSET	FCN	Unit	Restores factory default channel settings
AUTR	FCN	Channel	Enable/disable auto-scaling function
SAVS	FCN	Unit	Saves the current settings to NVRAM

Command type definitions;

- R/W the setting can be read from or written to the unit or channel.
- R The information can only be read from the unit or channel.
- FCN The command invokes a function in the unit.

4-9. Command Format

The 482C24 communication protocol incorporates the concept of 'Directed' and 'Global' commands at both the Unit and Channel level with the following characteristics;

- Unit or Channel numbers =0 are global commands that affect either all units or all channels of a particular unit or both.
- Directed commands that set a unit parameter are always acknowledged (ACK) with an ASCII message that indicates '<Unit#>:<CMD>:ok' if implemented with no errors or NAK with; <Unit#>:<CMD>:=<error#>' if an error was encountered.
- Directed commands that request a particular parameters setting (query) result in a query response being returned
- No response is ever given to a Global Unit command.

Command Format:

'Unit#:Ch#:Cmd[=|?]{<value1>{,< value2>}}}{;Ch#:Cmd[=|?]{<value1>{,< value2>}}}\n\r

- Each message must be preceded by a Unit# & Channel# (both of which could be 0)
- Messages may contain multiple commands separated by a semicolon ';'.
- The second and subsequent commands in a message shall not contain a unit number but shall contain a channel number.
- Each command in a message will evoke a response message if one is warranted (not global)
- Query's ('?') can only be directed to one unit but if the channel=0 then each channel's setting will be returned in the order 0-MAXCHANNELS separated by a ':'

Command examples:

```
1:0:GAIN=100.2\r\n unit 1,all channels gain set to 100.2

1:1:GAIN=100.2;2:GAIN=120.3\r\n unit 1, channel 1 gain = 100.2; channel 2 gain = 120.3

1:3:GAIN=100.2;0:FLTR=1\r\n unit 1, channel 3 gain = 100.2; all channel's filter = ON
```

General Query Response Format

```
Unit#:Cmd:Ch#=<value>{; Ch#=<value>}...>{; Ch#=<value>}...\r\n
```

Responses to a query with a channel number=0 will return the setting of each channel in a list separated by semicolons ':'.

If the target of the query is a unit setting (ex. current excitation) then the channel number returned is the 1st channel of the board that processed the command.

4-10. Commands

GAIN

SET GAIN: This command sets the programmable gain of a channel. The gain may be set to any setting within the 0.1 to 200 range for the incremental option included on 482C24.

Setting:

The amplifier gain can be set directly by sending a Gain command:

```
1:0:GAIN=100.2\r (unit 1,all channels gain set to 100.2)
```

When a channels gain is set directly the unit will adjust the FSI parameter of the gain equation using the following equation; FSI = (((FSO*1000)/Gain)/Sens)) to ensure it remains valid.

Setting Response: 1:GAIN:ok

Query:

The Gain query returns all of the parameters used to determine it in a single response

Query Format: Unit#:Ch#:CMD?

Response format: Unit#:Cmd:Ch#:=Gain:SENS:FSO:FSI;

Query: 1:5:GAIN?

Response: 1:GAIN:5= 5.0: 10.0: 10.0: 200.0;

Global Gain Ouery: 1:0:GAIN?

<u>Global Gain Response</u>: **1:GAIN:1**= 5.0: 10.0: 10.0: 200.0;**2**= 5.0: 10.0: 10.0: 200.0;**3**= 5.0: 10.0: 10.0: 200.0;**4**= 5.0: 10.0: 10.0: 200.0;

SENS

The SENS command provides a mechanism to have the transducer Sensitivity influence the Gain setting of the channel. Channel Gain is calculated using the equation;

Gain = FSO*1000/(FSI*SENS). If a Sensitivity is entered that caused the gain to exceed the amplifiers capability the FSI component will be adjusted to keep the equation valid.

Setting:

1:0:SENS=20.2\r\n (unit 1,all channels transducer sensitivity set to 20.2)

Setting Response: 1:SENS:ok

Query:

The Sens query returns the channels transducer sensitivity

Query Format: Unit#:Ch#:CMD?

Response format: Unit#:Cmd:Ch#:= SENS;

Query: 1:1:SENS?

<u>Response</u>: 1:SENS:1= 6.0;

Global Sens Query: 1:0:SENS?

<u>Global Sens Response</u>: 1:SENS:**1**= 6.0;**2**= 10.0;**3**= 10.0;**4**= 10.0;

FSCI

The FSCI command provides a scaling mechanism to automatically set the gain based on a known input level (in EU) and what output level (in Volts) you would like that Full Scale input level to be represented by. For instance 1000g's = 10Volts. These 2 values along with the transducer sensitivity set the gain. Channel Gain is calculated using the equation: G Gain = FSO*1000/(FSI*SENS).

Setting:

1:1:FSCI=1000.000\r\n (unit 1, channel 1 FSI set to 1000.0)

Setting Response: 1:FSCI:ok

Query:

The FSCI query returns the channels Full Scale Input value in engineering units

Query Format: Unit#:Ch#:CMD?

Response format: Unit#:Cmd:Ch#:= <fsci>;

Query: 1:1: FSCI?

<u>Response</u>: 1:FSCI:1=1000.0;

Global FSCI Query: 1:0:FSCI?

Global FSCI Response: 1:FSCI:1=1000.0;2=1000.0;3=1000.0;4=1000.0;

FSCO

The FSCO command provides a scaling mechanism to automatically set the gain based on a known input level (in EU) and what output level (in Volts) you would like that Full Scale input level to be represented by. For instance 1000g's = 10Volts. These 2 values along with the transducer sensitivity set the gain. Channel Gain is calculated using the equation: Gain = FSO*1000/(FSI*SENS).

Setting:

 $1:1:FSCO=10.000\r$ (unit 1, channel 1 FSI set to 10.0)

Setting Response: 1:FSCO:ok

Query:

The FSCO query returns the channels Full Scale Output Value in volts

Query Format: Unit#:Ch#:CMD?

Response format: Unit#:Cmd:Ch#:= <fsci>;

Query: 1:1: FSCO? Response: 1:FSCO:1=10.0;

Global FSCO Query: 1:0:FSCO?

Global FSCO Response: 1:FSCO:1=10.0;2=10.0;3=10.0;4=10.0;

INPT

The INPT command sets the input mode for a given channel. The mode selection is sent as an integer value. The possible input modes and their associated values are:

•	CHARGE	0
•	VOLTAGE	1
•	ICP®	2
•	Multi-Charge option of 10mV/pc sensitivity	3
•	Multi-Charge option of 1.0mV/pc sensitivity	4
•	Multi-Charge option of 0.1mV/pc sensitivity	5
•	Isolated ICP©	6
•	Isolated Multi-Charge option of 10mV/pc sensitivity	7
•	Isolated Multi-Charge option of 1.0mV/pc sensitivity	8
•	Isolated Multi-Charge option of 0.1mV/pc sensitivity	9
•	¹ / ₄ Bridge	10
•	½ Bridge	11
•	Full Bridge	12
•	Referenced Single Ended	13

NOTE: Not all input options are valid for all 482C models. Check the model specification for applicable input modes.

Setting:

1:1:INPT= 2 | r | n (unit 1, channel 1 input mode set to ICP)

Setting Response: 1:INPT:ok

Query:

The INPT query returns the channels input mode selection

Query Format: Unit#:Ch#:CMD?

Response format: Unit#:Cmd:Ch#:= <inpt>;

Query: 1:1:INPT?
Response: 1:INPT:1= 2;

Global INPT Query: 1:0:INPT?

Global INPT Response: 1:INPT:1= 2.0;2= 2.0;3= 2.0;4= 2.0;

IEXC

The IEXC command sets the current excitation level for ICP[®] mode. If the channel was in Voltage mode and this value gets set > 0, then the channel's input mode will switch to ICP[®] mode. Likewise if the channel is in ICP[®] mode and current excitation is turned off (0) then the channel input mode changes to Voltage. The current excitation value is sent as an integer value from 0 (off) to 20mA.

Setting:

1:1: $IEXC = 4 \mid r \mid n \text{ (unit 1, channel 1 set to } 4mA)$

Setting Response: 1:IEXC:ok

Query:

The IEXC query returns the units excitation value.

Query Format: Unit#:Ch#:CMD?

Response format: Unit#:Cmd:Ch#:= <IEXC>;

Query: 1:2:IEXC? Response: 1:IEXC:2=4;. Global IEXC Query: 1:0: IEXC?
Global IEXC Response: 1:IEXC:1=4;

FLTR

The FLTR command enables or disables the Input Filter.

The Input Filter value is sent as an integer value of either 0 -Disable or 1-Enable.

Setting:

2:1:FLTR= 1\r\n (unit 2, channel 1, Input Filter Enabled)

Setting Response: 2: FLTR:ok

Query:

The FLTR query returns the channels Input Filter selection

Query Format: Unit#:Ch#:CMD?

Response format: Unit#:Cmd:Ch#:= <0|1>;

Query: 2:1: FLTR? Response: 2:FLTR:1=1;

Global FLTR Query: 1:0: FLTR?

Global FLTR Response: 1:FLTR:1=1;2=0;3=0;4=0;

OFLT

The OFLT command enables or disables the Output Filter.

The Output Filter value is sent as an integer value of either 0 -Disable or 1-Enable.

Setting:

 $2:1:OFLT=1\r\n(unit 2, channel 1, Output Filter Enabled)$

Setting Response: 2: OFLT:ok

Query:

The FLTR query returns the channels Output Filter.

Query Format: Unit#:Ch#:CMD?

Response format: Unit#:Cmd:Ch#:= <0|1>;

Query: 2:1: OFLT?
Response: 2: OFLT:1=1;

Global OFLT Query: 1:0: OFLT?

<u>Global OFLT Response</u>: 1: OFLT:1=1;2=0;3=0;4=0;

CLMP

The CLMP command enables or disables the Clamp feature. When Clamp is disabled the channel is 'Buffered' The Clamp value is sent as an integer value of either 0 –Disable (buffered) or 1-Enable.

Setting:

2:1:CLMP= $1 \mid r \mid n$ (unit 2, channel 1, Clamp Enabled)

Setting Response: 2: CLMP:ok

Query:

The CLMP query returns the channels Clamp setting.

Query Format: Unit#:Ch#:CMD?

Response format: Unit#:Cmd:Ch#:= <0|1>;

Query: 1:1:CLMP? Response: 1:CLMP:1=0;

Global CLMP Query: 1:0:CLMP?

<u>Global CLMP Response</u>: 1:CLMP:1=0;2=0;3=0;4=0;

CPLG

The CPLG command sets the channel coupling to AC or DC mode.

The DC coupling option will attempt to remove a DC offset from the input signal by reading the bias and using an internal DAC to zero it. This function will be performed when the setting is changed from AC to DC.

The coupling value is sent as an integer value: 0 –AC, 1-DC.

Setting:

 $1:1:CPLG=1 \mid r \mid n (unit 1, channel 1, DC Coupled)$

Setting Response: 1: CPLG:ok

Query:

The CPLG query returns the channels coupling setting.

Query Format: Unit#:Ch#:CMD?

Response format: Unit#:Cmd:Ch#:= <0|1>;

Query: 1:1:CPLG? Response: 1: CPLG:1=0;

Global CPLG Query: 1:0: CPLG?

Global CPLG Response: 1: CPLG:1=0;2=0;3=0;4=0;

AZZR

The AZZR command is used to Auto Zero (input shorted) or Auto Balance (input connected) a channel that is DC coupled. This command invokes a function and therefore has no query capability. The function parameters are: 1=Auto Zero, 2=Auto Balance. (Auto Balance is only valid if the channel has a bridge input type selected).

Setting:

2:1:AZZR=1/r/n (unit 2, channel 1, Auto Zero)

Setting Response: 2:AZZR:ok

Query:

N/A

VEXC

The VEXC command sets the voltage excitation level for bridge and differential mode inputs.

The voltage excitation value is sent as a floating point number from 0.0 (off) to ± 12.0 Volts. If the value is sent as a negative number then the minus (-) Bridge Excitation will track the plus (+) Bridge Excitation setting. If it is sent as a Positive value then the minus (-) Bridge Excitation will be set to 0.

Setting:

1:1:VEXC=-10.0 \r\n (unit 1, channel 1, sets minus (-) Bridge Excitation and plus (+)Bridge Excitation to 10.0 volts – Bi-Polar)

1:1:VEXC= 10.0 |r|n (unit 1, channel 1, sets minus (-) Bridge Excitation to 0 and plus (+)Bridge Excitation to 10.0 volts – Uni-Polar)

Setting Response: 1:VEXC:ok

Ouerv:

The VEXC query returns the voltage excitation value.

Query Format: Unit#:Ch#:CMD?

Response format: Unit#:Cmd:Ch#:= <VEXC>;

Query: 1:1:VEXC?

Response: 1:VEXC:1=-10.0;

Global Query: 1:0: VEXC?

Global Response: 1:VEXC:1=-10.0;2=10.0;3=0.0;4=0.0;

CALB

The Calibration mode (CALB) command selects the calibration setting. For the bridge input 482C27 the options are OFF, Internal Shunt +, or Internal Shunt -. For other models that support calibration signal output, Internal Cal using internally generated 100 Hz or 1 kHz sine wave signals and External Cal are available.

The CALB value is sent as an integer value of either 0 –Disable, 1-1000 Hz Enable, 2-100 Hz Enable, 3-External Cal, 4 -Internal Shunt +, or 5 – Internal Shunt -.

Setting:

1:1: CALB= 4\r\n (unit 1, channel 1, Internal Shunt Cal +)

Setting Response: 1:CALB:ok

Query:

The CALB query returns the channels calibration setting.

Query Format: Unit#:Ch#:CMD?

Response format: Unit#:Cmd:Ch#:= <0|1>;

Query: 1:1: CALB? Response: 1: CALB:1=4; Global Query: 1:0:CALB?

Global Response: 1:CALB:1=4;2=0;3=0;4=0;

RTED

The RTED query returns the TEDS information that is stored in the EEPROM of a memory chip in the sensor or other, TEDS capable, in-line module attached to a specific channel. Following is a list of recognized TEDS chips that can be read with the RTED command;

DS2430A	FC = 0x14	1 page	Plus an 8 byte Application register
DS2431	FC = 0x2D	4 Pages	
DS2433	FC = 0x23	16 Pages	
DS28EC20	FC = 0x43	80 Pages	

This command will also read the Application Register Status of a DS2430A chip, if one is encountered, to see if it indicates the 64 bit Application Register has data in it. If so it will read the Application register contents and return it followed by the contents of the TEDS EEPROM.

The RTED command requires a page number parameter for chips larger than 128 bytes (e.g.DS2433 & DS28EC20). The page numbers must be expressed as two decimal characters starting at 00 and be appended to the end of the command after the '?'. However, in order to be backwards compatible, the page number is only used if the chip is DS2433 or DS28EC20, it is not necessary for DS2430A or DS2431 chips.

NOTE: The 1st byte of the DS2430A EEPROM data should contain the checksum of both the Application Register contents and the EEPROM contents if the TEDS is 1451.4 compliant. Additionally, for the larger capacity chips that do not have an application register the 1st byte should contain the CS of that page.

No attempt is made to validate or interpret TEDS data with this command.

Setting:

N/A - Command is Read only (the WTED command writes TEDS data)

Query:

The RTED command query returns the TEDS data associated with the specified channel. This command must be directed to a specific channel. The RTED response varies depending on the chip encountered:

DS2430A: The 1st byte of the response will return an indicator (0 or 1) that specifies if the DS2430A Application register has been used to store the basic TEDS data (1) and up to 40 bytes in ASCII Hex format (8 bytes of Application register content if it contained data and 32 bytes of the EEPROM content).

DS2431: The response will return the Family code 45(decimal) followed by 128 bytes of EEPROM data (4 pages of 32 bytes each) in 2 character hex notation.

DS2433 or **DS28EC20**: The response will return the appropriate family code followed by the specified page of EEPROM data -32 bytes in in 2 character hex notation.

Query Format: Unit#:Ch#:CMD?<Page>

<u>Response format</u>: <Unit#>:RTED:<Ch#>= <APP Reg Status or Family code in decimal>:<APP Reg Contents (8 hex bytes if APP Reg Status=1)><DS2430A EEPROM Contents (32 hex bytes)>

Where: APP Reg Status for a DS2430 chip=1 if the APP Register had data or 0 if it did not. For all other chips this value is the <u>Family Code</u> of the chip which should be used to read the appropriate number of pages from the chip. (If value=0 or 1 then assume FC =0x14).

Query example 1: 1:2:RTED?00 ;read teds on channel 2 starting at the 1st page (0)) Response: (for a DS2430A TEDS chip on channel 2 with valid app register data)

 $1:RTED:2=\underline{\textbf{1}}:168010a0097500008e64d059e6a427204aa7394a0a73215aa06d01903f97e6b7dcf9bc0240000000$

Query example 2: 1:1:RTED?00

<u>Response example 2</u>: Teds read on a sensor with a DS2431 chip (Family code 45 (0x2D) is the 1st item after the '=' in the response separated from the memory contents with a ':'. It will return all 4 pages of a DS2431 chip with 1 read command

WTED

The WTED command writes a string of bytes to the EEPROM memory of a TEDS capable chip, contained in a sensor or inline module, attached to the specified channel. The command can transfer up to 1 page, 32 bytes, and the contents of an application register, 8 bytes, if one exists (DS2430A only if it is not locked). Following is a list of Maxim TEDS chips that can be written to with the WTED command;

DS2430A	FC = 0x14	1 Page	Plus an 8 byte Application Register
DS2431	FC = 0x2D	4 Pages	
DS2433	FC = 0x23	16 Pages	
DS28EC20	FC = 0x43	80 Pages	

The WTED command requires a page number parameter, for all chips, to identify which page will receive the data. Page numbering starts at 0.

NOTE: No attempt is made to validate or interpret TEDS data with this command, it just writes bytes.

Setting:

1:1:WTED=36:0:0:43:23:64:83:160:89:88:9:0:100:128:25:216:154:232:225:18:128:31:17:0:224:46:90: 160:104:161:142:199:100:51:218:36

Command interpretation:

<Unit Id>:<Channel Id>: WTED=<TEDS data to write> with the following format.

Note: all values are decimal.

B0 – Message Length - Total bytes in message including this byte.

B1 - 1st 8 bytes go in Application Register? 0=FALSE | 1=TRUE

B2 – Page Number (0 for DS2430A | 0-3 for DS2431 | 0-15 for DS2433 | 0-79 for DS28EC20

B3 - Bn-1 TEDS page content (up to 40 bytes - 8 app register bytes plus 32 EEPROM bytes)

Bn – Checksum (Simple checksum of all bytes – least significant byte of 16 bit summation)
In the example above, the summation of 36...218 = 3364 = 0xD24; LSB=0x24=36 decimal

Setting Response: 1:WTED:ok

Query:

Use the RTED command to query TEDS data

ALLC

The ALLC command is used to read several channel settings at once.

Setting:

N/A - Command is Read only

Query:

This command must be a directed command use of the global channel indicator is not allowed.

Query Format: Unit#:Ch#:CMD?

Response format: Unit#:Cmd:Ch#:= GAIN:<Gain value>; SENS:< SENS value>; FSCI:< FSCI value>; FSCO:< FSCO value>; INPT:< INPT value>; FLTR:< FLTR value>; IEXC:< IEXC value>; OFLT:< OFLT value>; CPLG:< CPLG value>; CLMP:< CLMP value>; CALB:< CALB value>; VEXC:< VEXC value>; SWOT < SWOT value>

Query: 1:1:ALLC?

Response:1:ALLC:1=GAIN 1.0; SENS:10.0; FSCI:1000.0; FSCO:10.0; INPT:2.0; FLTR:0; IEXC:4; OFLT:0; CPLG:0; CLMP:0; CALB:0; VEXC: 0.0; SWOT:0;

RBIA

The RBIA command is used to read all channels Bias Levels.

Setting:

N/A – Command is Read only

Query:

This command is a global command and will return all channel bias readings regardless of the channel id in the command.

Query Format: Unit#:Ch#:RBIA?

Response format: Unit#:Cmd:Ch#:=CH1 bias;... CHn#:=CHn bias;

Query: 1:1:RBIA?

Query Response: 1:RBIA:1= 25.5;2= 25.5;3= 25.5;4= 25.5;

CHRD

The CHRD command is used to read all channels output levels.

Setting:

N/A - Command is Read only

Query:

This command is a global command and will return all channel A/D readings regardless of the channel id in the command.

Query Format: Unit#:Ch#:CHRD?

Response format: Unit#:Cmd:Ch#:=CH1 A/D;... CHn#:=CHn A/D;

Query: 1:0:CHRD?

<u>Query Response</u> 1:CHRD:1= 4.049;2=5.338;3=2.137;4=10.373;

SWOT

The Switched Output (SWOT) command selects which channel is switched to the switched output BNC for monitoring purposes as well as its normal analog output. This is a unit command so the channel designation in the command protocol is ignored

The switched output value is sent as an integer value: 0-OFF; or 1-MAX Channels to designate which channel is switched.

Setting:

1:0:SWOT= 4\r\n (unit 1, channel NA, Channel 4 is switched to the switched output BNC)
Setting Response: 1: SWOT:ok

Query:

The SWOT query returns all channels coupling setting.

Query Format: Unit#:Ch#:CMD?

Response format: Unit#:Cmd:Ch#:= <channel # or 0=OFF>;

Query: 1:1:SWOT? Response: 1:SWOT:1=4;

STUS

The STUS command is used to read the unit and all channel status indicators.

Setting:

N/A – Command is Read only

Query:

This command is a global command and will return all channel bias readings regardless of the channel id in the command.

Query Format: Unit#:Ch#:STUS?

Response format: Unit#:Cmd:Ch#:<unit status bit map>;<CH1 status bit map>;...;<CHn status bit

map>;

Query: 1:1:STUS?

<u>Query Response</u>: 1:STUS:1:0;1;5;5;5;

Where:

Unit Bit 0 = 1 = BAD EEPROM read for channel settings on power up Unit Bit 1 = 1 = BAD EEPROM read for Unit options on power up Unit Bit 2 = 1 = BAD EEPROM read for cal factors on power up

For Unit bit map 0=no errors

Channel Bit 0= Short input fault (0=Fault; 1 = no fault) Channel Bit 1= Open input fault (0=Fault; 1 = no fault)

Channel Bit 2= Overload condition (0=Overload; 1 = no Overload)

For channel bit map 7=no errors

UNIT

The UNIT query returns the unit configuration information which includes the installed options, unit number, Model id and starting channel number

Query Format: Unit#:Ch#:CMD?

Response format: Unit#:Cmd: Model string: Firmware Ver string: Serial Number: Cal Date: Filter Corner: Unit#:#channels: Starting Ch#: Gain Option byte, Input Option Byte, Filter option byte,Misc1 option

byte,Misc2 option byte<cr><lf>

Query: 1:1:UNIT?

Response: 1:UNIT:482C24 :FW v4A2.5 :1234:12-17-2015

 $:1:4:1:16,4,0,207,2:0.00000:0.00000:0.00000:0.00000:0.00000:0.00000:0.00000:0.00000:0.00000: \r\n$

Model & Firmware version strings are self-explanatory. Following are: Serial Number (U16): Cal Date (10 character string): Filter corner (kHz)

Unit Id: Number of Channels: Starting Channel Number followed by the option bytes:

Gain Options

0x01	Fixed x1
0x02	Fixed x5
0x04	Fixed x10
80x0	Variable Fixed (x1,x10,x100)
0x10	incremental .1-200
0x20	Fine Gain .0025-200
0x40	Fine Gain .0025-1000
0x01	All charge
0x02	ICP VOLT CHG
0x04	ICP VOLT
80x0	Internal Cal
0x10	External Cal
0x20	Isolation
	0x02 0x04 0x08 0x10 0x20 0x40 0x01 0x02 0x04 0x08 0x10

Filter Options					
OPT_FILTER_IN	0x01	Input filter (time constant)			
OPT_FILTER_OUT	0x02	Output filter			
OPT_FILTER_FIXLP	0x04	Fixed LP filter			
OPT_FILTER_PGMELP	80x0	Programmable LP Elliptical filter			
OPT_FILTER_PGMBTR	0x10	Programmable LP Butterworth filter			
Miscellaneous Options					
OPT_MISC_COUPLING	0x01	AC/DC coupling			
OPT_MISC_CLAMP	0x02	Clamp			
OPT_MISC_TEDS	0x04	TEDS			
OPT_MISC_IEXC	80x0	current excitation			
OPT_MISC_SINTG	0x10	Single Integration			
OPT_MISC_DINTG	0x20	Double Integration			
OPT_MISC_MUX	0x40	Mux /Switch-out			
OPT_MISC_DISPLAY	0x80	FP Display			
Miscellaneous 2 Options					
OPT_MISC2_IM33893	0x01	Old ISO Board installed			
OPT_MISC2_A2D	0x02	A/D installed			
OPT_MISC2_MULTIBDwDSP	0x04	Multi-board with display			
OPT_MISC2_NOPWRBTN	0x80	ignore soft power button operation			

UNID

The UNID command is used to set the units ID number. The Unit Id number is critical to remote communications since it indicates to the unit which commands it should accept and respond to. Units are typically shipped with a unit id of 1. If more than one unit is in the system and they will be communicated with remotely the user must set a unique id in each unit. This can be done through the front panel interface, if one exists, or by connecting to each unit individually and sending this command.

Setting:

 $1:1:UNID=2\r\n\ (unit\ 1, channel\ 1, New\ ID=2)$

Setting Response: 2:UNID:ok

NOTE: The new Unit Id becomes effective immediately

Query:

This command can be sent as a query but its usefulness is marginal being as it is a directed command and as such it is necessary to include the Unit Id in the command and the response will simply validate the commands unit id parameter.

Query Format: Unit#:Ch#:UNID?

Response format: Unit#:Cmd:Ch#:=unit id

Query: 2:1:UNID?

Query Response: 2:UNID:1=2;

LEDS

The LEDS command is used to test the LED functionality of the front panel. When sent as a command the LED's on the front panel will flash 3 times. This command invokes a function and therefore has no query capability.

Setting:

 $2:1:LEDS=0\rdotr(n (unit 2, channel 1, Any value))$

Setting Response: 2:LEDS:ok

Query:

N/A

RSET

The RSET command is used to restore the factory default channel settings. This command invokes a function and therefore has no query capability.

Setting:

 $2:1:RSET = 0 \mid r \mid n$ (unit 2, channel 1, Any value)

Setting Response: 2:RSET:ok

Query:

N/A

The factory Defaults are:

- Gain= 1.0
- Sensitivity=10.0
- Full Scale input= 1000.0
- Full Scale output= 10.0
- Input Mode = ICP
- Input Filter=Disabled
- Current excitation=4.0mA
- Output Filter=Disabled
- Coupling =AC
- Clamp=OFF
- Internal Reference Oscillator=OFF

AUTR

The AUTR command invokes the Auto-Scaling function. With this command, the programmable gain is adjusted to give the largest signal amplitude output without causing an overload condition. The signals are checked internally; if there is an overload, the signal is stepped down and checked again.

Possible settings are: **0=off,1-on,2=immediate**. The Immediate option causes the auto scale function to execute one time and then turns off the function automatically. When Auto scale is 'ON' the unit will continue to invoke the function until the function is turned OFF with a subsequent command.

Setting:

2:1: $AUTR = 1 \mid r \mid n$ (unit 2, channel 1, Auto Scaling ON)

Setting Response: 2:AUTR:ok

Query:

Query Format: Unit#:Ch#: AUTR?

<u>Response format</u>: Unit#:Cmd:Ch#:=current state (0=off,1-on,2=immediate)

Query: 2:1:AUTR?

Query Response: 2:AUTR:1=0;

SAVS

The SAVS command is used to store the current channel setting as the default settings that will be restored on power up. This command invokes a function and therefore has no query capability.

Setting:

 $2:1:SAVS = 0 \mid r \mid n \pmod{2}$, channel 1, Any value)

Setting Response: 2:SAVS:ok

Query: NA

Communication Responses

Typically the unit will return **<Unit>:<Cmd String>:OK** when the command is successful. Errors are indicated with negative numbers. The unit may return one of the following:

<Unit>:<Cmd String>:OK<CR> <LF>

Represents that the last command was entered in the correct format and was performed properly.

<Unit>:<Cmd String>:-1<CR> <LF>

Option Error. The unit is not equipped with the option necessary to implement the command sent

<Unit>:<Cmd String>:-2<CR> <LF>

Channel Error. The channel number in the command is invalid.

<Unit>:<Cmd String>:-3<CR> <LF>

Command Error. The command is not recognized.

<Unit>:<Cmd String>:-4<CR> <LF>

Unit Error. The unit number in the command is invalid.

<Unit>:<Cmd String>:-5<CR> <LF>

Unit Error. The function invoked by the command encountered an error or a query only command (ex. RBIA) was sent as a setting.

<Unit>:<Cmd String>:-6<CR> <LF>

Command Parameter Error. A channel setting parameter was found to be out of range.

<Unit>:<Cmd String>:-10<CR> <LF>

legacy error from bad power supply problem w/482M179 */

<Unit>:<Cmd String>:-11<CR> <LF>

Bridge DC Offset ERR - Illegal Setting

<Unit>:<Cmd String>:-12<CR> <LF>

Bridge DC Offset ERR - Too Many iterations

<Unit>:<Cmd String>:-13<CR> <LF>

ICP DC Offset ERR - Bad RDG

<Unit>:<Cmd String>:-14<CR> <LF>

ICP DC Offset ERR - Too Many iterations

<Unit>:<Cmd String>:-15<CR> <LF>

Balance Request, channel not in Bridge mode - Illegal Setting

<Unit>:<Cmd String>:-16<CR> <LF>

Zero Request, channel not in Bridge mode or ICP/volt - Illegal Setting

<Unit>:<Cmd String>:-17<CR> <LF>

iEXc request while channel in Bridge/Diff mode,- Illegal Setting

<Unit>:<Cmd String>:-18<CR> <LF>

vEXc request while channel in ICP/Volt mode,- Illegal Setting

<Unit>:<Cmd String>:-19<CR> <LF>

TEDS read request when Channel is not in ICP or Voltage Mode

<Unit>:<Cmd String>:-20<CR> <LF>

TEDS Chip Search algorithm Failed

<Unit>:<Cmd String>:-21<CR> <LF>

TEDS Write Buffer too Big

<Unit>:<Cmd String>:-22<CR> <LF>

TEDS Write Buffer CS Failure